

ON GENERAL FUZZY RECOGNIZERS

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ABSTRACT. In this paper, we define the concepts of general fuzzy recognizer, language recognized by a general fuzzy recognizer, the accessible and the coaccessible parts of a general fuzzy recognizer and the reversal of a general fuzzy recognizer. Then we obtain the relationships between them and construct a topology and some hypergroups on a general fuzzy recognizer.

1. Introduction and Preliminaries

The concept of fuzzy automata was introduced by Wee in 1967 [16]. Wee and Fu [17] first introduced fuzzy recognizers with a non-fuzzy initial states, non-fuzzy final states and non-fuzzy inputs.

Let Σ be a set. A word in Σ is the product of a finite sequence of elements in Σ . Λ will denote the empty word and Σ^* the set of all words on Σ . The length $\ell(x)$ of the word $x \in \Sigma^*$ is the number of its letters, so $\ell(\Lambda) = 0$. For a nonempty set X , $\tilde{P}(X)$ will denote the set of all fuzzy sets on X and $P(X)$ will denote the set of all subsets on X .

A deterministic finite-state automaton is a five-tuple denoted as $A = (Q, \Sigma, f, T, s)$, where Q is a finite set of states, Σ is a finite set of input symbols, f is the state transition function, from $Q \times \Sigma$ into Q T is a subset of Q of accepting states and $s \in Q$ is the initial state.

A word $x = x_1x_2 \dots x_n \in \Sigma^*$ is said to be accepted by A if there exist states q_0, q_1, \dots, q_n satisfying

- (1) $q_0 = s$
- (2) $f(q_{i-1}, x_i) = q_i$ for $i = 1, 2, \dots, n$,
- (3) $q_n \in T$.

The empty word is accepted by A if and only if $s \in T$.

A nondeterministic finite-state automaton is a five-tuple denoted as $A = (Q, \Sigma, f, T, s)$, where Q is a finite set of states, Σ is a finite set of input symbols, f is the state transition function from $Q \times \Sigma$ into $P(Q)$, T is a subset of Q of accepting states and $s \in Q$ is the initial state.

A fuzzy finite-state automaton (FFA) is a six-tuple $\tilde{F} = (Q, \Sigma, R, Z, \delta, \omega)$, where Q is a finite set of states, Σ is a finite set of input symbols, R is the initial state of

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\tilde{F} , Z is a finite set of output symbols, $\delta : Q \times \Sigma \times Q \rightarrow [0, 1]$ is the fuzzy transition function which is used to map a state (current state) into another state (next state) upon an input symbol, attributing a value in the interval $[0, 1]$ and $\omega : Q \rightarrow Z$ is the output function. Associated with each fuzzy transition, there is a membership value in $[0, 1]$ called the weight of the transition. Transition from state q_i (current state) to state q_j (next state) upon input a_k is denoted by $\delta(q_i, a_k, q_j)$.

We use $\delta(q_i, a_k, q_j)$ to refer both to a transition and its weight in the sense that whenever $\delta(q_i, a_k, q_j)$ is used as a value, it refers to the weight of the transition, and otherwise, specifies the transition itself. The set of all transitions of \tilde{F} will be denoted by Δ . The above definition is generally accepted as a formal definition of an FFA [10], [13], [14].

In 2004, M. Doostfatemeleh and S.C. Kremer extended the notion of fuzzy automata and introduced the notion of general fuzzy automata [6].

Santos [15] and Mizumoto [12] studied various fuzzy recognizers (automata) with fuzzy initial states, non-fuzzy final states and non-fuzzy inputs.

Malik, Mordeson and Sen introduced fuzzy recognizers in [11] with fuzzy initial states, fuzzy final states and non-fuzzy inputs.

Kumbhojkar and Chaudhari characterized words recognized by fuzzy recognizer and proved fuzzy recognizability of several crisp sets [9].

In this paper, by using [1],[2],[3],[7] and [9], we extend the notion of fuzzy recognizer and introduce the notion of general fuzzy recognizer and construct a topology and some hypergroups on a general fuzzy recognizer.

Definition 1.1. [6] A general fuzzy automaton (GFA) is an eight-tuple machine $\tilde{F} = (Q, \Sigma, \tilde{R}, Z, \tilde{\delta}, \omega, F_1, F_2)$, where

- (i) Q is a finite set of states, $Q = \{q_1, q_2, \dots, q_n\}$,
- (ii) Σ is a finite set of input symbols, $\Sigma = \{a_1, a_2, \dots, a_m\}$,
- (iii) \tilde{R} is the set of fuzzy start states, $\tilde{R} \in \tilde{P}(Q)$,
- (iv) Z is a finite set of output symbols, $Z = \{b_1, b_2, \dots, b_k\}$,
- (v) $\omega : Q \rightarrow Z$ is the output function,
- (vi) $\tilde{\delta} : (Q \times [0, 1]) \times \Sigma \times Q \rightarrow [0, 1]$ is the augmented transition function,
- (vii) $F_1 : [0, 1] \times [0, 1] \rightarrow [0, 1]$ is the membership assignment function,
- (viii) $F_2 : [0, 1]^* \rightarrow [0, 1]$ is called the multi-membership resolution function.

We note that the function $F_1(\mu, \delta)$ has two parameters μ and δ , where μ is the membership value of a predecessor and δ is the weight of a transition. In this definition, the process that takes place upon the transition from state q_i to q_j on input a_k is represented as:

$$\mu^{t+1}(q_j) = \tilde{\delta}((q_i, \mu^t(q_i)), a_k, q_j) = F_1(\mu^t(q_i), \delta(q_i, a_k, q_j)).$$

This means that the membership value (mv) of the state q_j at time $t+1$ is computed by the function F_1 using both the membership value of q_i at time t and the weight of the transition.

The usual options for the function $F_1(\mu, \delta)$ are $\max\{\mu, \delta\}$, $\min\{\mu, \delta\}$ and $(\mu + \delta)/2$.

The multi-membership resolution function resolves the multi-membership active states and assigns a single membership value to them.

Let $Q_{act}(t_i)$ be the fuzzy set of all active states at time t_i , $\forall i \geq 0$. We have $Q_{act}(t_0) = \tilde{R}$ and

$$Q_{act}(t_i) = \{(q, \mu^{t_i}(q)) : \exists q' \in Q_{act}(t_{i-1}), \exists a \in \Sigma, \delta(q', a, q) \in \Delta\}, \forall i \geq 1.$$

Since $Q_{act}(t_i)$ is a fuzzy set, in order to show that a state q belongs to $Q_{act}(t_i)$ and T is a subset of $Q_{act}(t_i)$, we should write: $q \in \text{Domain}(Q_{act}(t_i))$ and $T \subset \text{Domain}(Q_{act}(t_i))$.

Hereafter, we simply denote them as: $q \in Q_{act}(t_i)$ and $T \subset Q_{act}(t_i)$.

The combination of the operations of functions F_1 and F_2 on a multi-membership state q_j leads to the multi-membership resolution algorithm.

Algorithm 1.2. [6] (Multi-membership resolution) If there are several simultaneous transitions to the active state q_j at time $t + 1$, the following algorithm will assign a unified membership value to it:

(1) Each transition weight $\delta(q_i, a_k, q_j)$ together with $\mu^t(q_i)$, will be processed by the membership assignment function F_1 , and will produce a membership value. Call this v_i .

$$v_i = \tilde{\delta}((q_i, \mu^t(q_i)), a_k, q_j) = F_1(\mu^t(q_i), \delta(q_i, a_k, q_j)).$$

(2) These membership values are not necessarily equal. Hence, they need to be processed by the multi-membership resolution function F_2 .

(3) The result produced by F_2 will be assigned as the instantaneous membership value of the active state q_j ,

$$\mu^{t+1}(q_j) = F_2 \left[\sum_{i=1}^n v_i \right] = F_2 \left[\sum_{i=1}^n F_1(\mu^t(q_i), \delta(q_i, a_k, q_j)) \right].$$

where

- n is the number of simultaneous transitions to the active state q_j at time $t + 1$.
- $\delta(q_i, a_k, q_j)$ is the weight of a transition from q_i to q_j upon input a_k .
- $\mu^t(q_i)$ is the membership value of q_i at time t .
- $\mu^{t+1}(q_j)$ is the final membership value of q_j at time $t + 1$.

Definition 1.3. [18] Let $\tilde{F} = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}, F_1, F_2)$ be a general fuzzy automaton. We define max-min general fuzzy automata as $\tilde{F}^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2)$ such that :

$$\tilde{\delta}^* : Q_{act} \times \Sigma^* \times Q \rightarrow [0, 1]$$

where $Q_{act} = \{Q_{act}(t_0), Q_{act}(t_1), Q_{act}(t_2), \dots\}$ and for all $i \geq 0$,

$$\tilde{\delta}^*((q, \mu^{t_i}(q)), \Lambda, p) = \begin{cases} 1, & q = p, \\ 0, & \text{otherwise} \end{cases}$$

Also, if the input at time t_i be u_i , where $u_i \in \Sigma, \forall 1 \leq i \leq n$, then

$$\tilde{\delta}^*((q, \mu^{t_{i-1}}(q)), u_i, p) = \tilde{\delta}((q, \mu^{t_{i-1}}(q)), u_i, p),$$

$$\tilde{\delta}^*((q, \mu^{t_{i-1}}(q)), u_i u_{i+1}, p) = \bigvee_{q' \in Q_{act}(t_i)} (\tilde{\delta}((q, \mu^{t_{i-1}}(q)), u_i, q') \wedge \tilde{\delta}((q', \mu^{t_i}(q')), u_{i+1}, p)),$$

and recursively

$$\tilde{\delta}^*((q, \mu^{t_0}(q)), u_1 u_2 \dots u_n, p) = \bigvee \{ \tilde{\delta}((q, \mu^{t_0}(q)), u_1, p_1) \wedge \tilde{\delta}((p_1, \mu^{t_1}(p_1)), u_2, p_2) \wedge \dots \wedge \tilde{\delta}((p_{n-1}, \mu^{t_{n-1}}(p_{n-1})), u_n, p) \mid p_1 \in Q_{act}(t_1), p_2 \in Q_{act}(t_2), \dots, p_{n-1} \in Q_{act}(t_{n-1}) \}.$$

If $q \in Q_{act}(t_i)$, we should write q belongs to an element of Q_{act} . Hereafter, we simply denote it as: $q \in Q_{act}$.

Definition 1.4. [10] The mapping $\rho : \Sigma^* \longrightarrow \Sigma^*$ is called a reversal of Σ^* if the following conditions hold :

- (i) $\rho(\Lambda) = \Lambda$,
- (ii) $\rho(a) = a$,
- (iii) $\rho(xa) = \rho(a)\rho(x)$,
- $\forall a \in \Sigma$ and $x \in \Sigma^*$.

Corollary 1.5. If $\rho : \Sigma^* \longrightarrow \Sigma^*$ be a reversal mapping, then $\rho(\rho(x)) = x$.

Proof. IT is streightforward by induction on the length of x .
Let $A \subseteq \Sigma^*$ and $\rho : \Sigma^* \longrightarrow \Sigma^*$ be the reversal mapping. Let

$$A^\rho = \{\rho(x) : x \in A\}. \quad \square$$

Definition 1.6. [8] Let X be an arbitrary set. The function $\psi : P(X) \longrightarrow P(X)$ is called a closure operator on X , if for any two elements A and B of $P(X)$, we have

- (i) $\psi(\emptyset) = \emptyset$,
- (ii) $A \subseteq \psi(A)$,
- (iii) $\psi(A \cup B) = \psi(A) \cup \psi(B)$,
- (iv) $\psi(\psi(A)) = \psi(A)$.

Definition 1.7. [8] A subset τ of $P(X)$ is called a topology on X if

- (i) $\emptyset, X \in \tau$,
- (ii) If $A_1, A_2 \in \tau$, then $A_1 \cap A_2 \in \tau$,
- (iii) If $A_i \in \tau, \forall i \in I$, then $\bigcup_{i \in I} A_i \in \tau$.

Definition 1.8. [5] A nonempty set H endowed with a hyperoperation $\circ : H^2 \rightarrow P^*(H)$ is called a hypergroupoid where $P^*(H)$ is the set of all nonempty subsets of H . The image of the pair $(a, b) \in H^2$ is denoted by $a \circ b$ and is called the hyper-product of a and b . If A and B are nonempty subsets of H , then $A \circ B = \bigcup_{a \in A, b \in B} a \circ b$.

Definition 1.9. [4] The hypergroupoid $\langle H, \circ \rangle$ is called semihypergroup if the hyperoperation " \circ " is associative. A semihypergroup $\langle H, \circ \rangle$ is called hypergroup

if

$$H \circ a = a \circ H = H, \quad \forall a \in H.$$

2. On General Fuzzy Recognizers

In this article, we introduce some operations which will simplify proofs of quite a few theorems proved in this paper.

Definition 2.1. Let $\tilde{F}^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2)$ be a max-min general fuzzy automaton, $\alpha : Q \rightarrow [0, 1]$, $\tau : Q \rightarrow [0, 1]$, $x \in \Sigma^*$ and $A \subseteq \Sigma^*$. Define

(i) $\alpha * x : Q \rightarrow [0, 1]$ by

$$(\alpha * x)(p) = \bigvee \{ \alpha(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) : q \in Q_{act} \}$$

$\forall p \in Q$,

(ii) $\alpha * A : Q \rightarrow [0, 1]$ by

$$\alpha * A = \bigcup_{x \in A} \alpha * x,$$

(iii) $\alpha * x^{-1} : Q_{act} \rightarrow [0, 1]$ by

$$(\alpha * x^{-1})(p) = \bigvee \{ \alpha(q) \wedge \tilde{\delta}^*((p, \mu^t(p)), x, q) : q \in Q \}$$

$\forall p \in Q_{act}$,

(vi) $\alpha * A^{-1} : Q_{act} \rightarrow [0, 1]$ by

$$\alpha * A^{-1} = \bigcup_{x \in A} \alpha * x^{-1},$$

(v)

$$\alpha^{-1} \circ \tau = \{ x \in \Sigma^* : \alpha(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \tau(p) > 0 \\ \text{for some } q \in Q_{act}, p \in Q \}.$$

Definition 2.2. A general fuzzy recognizer is a ten-tuple $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$, where

- (i) $\tilde{F}^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2)$ is a max-min general fuzzy automaton,
- (ii) ι is a fuzzy subset of Q , called the initial fuzzy state,
- (iii) ζ is a fuzzy subset of Q , called the fuzzy subset of final states.

Definition 2.3. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer and $x \in \Sigma^*$. Then x is said to be recognized by \tilde{F}_r^* if

$$\bigvee \{ \iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) : q \in Q_{act}, p \in Q \} > 0.$$

Definition 2.4. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer and

$$L(\tilde{F}_r^*) = \{ x \in \Sigma^* : x \text{ is recognized by } \tilde{F}_r^* \}.$$

$L(\tilde{F}_r^*)$ is called the language recognized by the general fuzzy recognizer \tilde{F}_r^* .

Theorem 2.5. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. Then

$$L(\tilde{F}_r^*) = \{x \in \Sigma^* : \iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0 \text{ for some } q \in Q_{act}, p \in Q\}.$$

Proof. The proof is obvious. \square

Theorem 2.6. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. We define the equivalence relation R on Σ^* by

$$xRy \iff \tilde{\delta}^*((q, \mu^t(q)), x, p) = \tilde{\delta}^*((q, \mu^t(q)), y, p) : \exists q \in Q_{act}, p \in Q.$$

Let $B(x) = \{y \in \Sigma^* : xRy\}$, $B(D) = \bigcup_{x \in D} B(x)$. We define

$$\begin{aligned} B : P(\Sigma^*) &\longrightarrow P(\Sigma^*) \\ D &\longrightarrow B(D). \end{aligned}$$

Then B is a closure operator on Σ^* .

Proof. (i) $B(\emptyset) = \emptyset$.

(ii) Let $x \in D$. Since xRx , $x \in B(x) \subseteq B(D)$. Thus, $D \subseteq B(D)$.

(iii) $B(C \cup D) = \bigcup_{x \in C \cup D} B(x) = (\bigcup_{x \in C} B(x)) \cup (\bigcup_{x \in D} B(x)) = B(C) \cup B(D)$.

(iv) By (ii), we have $B(D) \subseteq B(B(D))$. Conversely, let $x \in B(B(D))$. Then there exists $y \in B(D)$ such that $x \in B(y)$. Thus $y \in B(x_1)$, for some $x_1 \in D$. Consequently, xRy and yRx_1 . Since R is an equivalence relation, xRx_1 . Thus $x \in B(x_1) \subseteq B(D)$. Therefore $B(B(D)) \subseteq B(D)$. \square

Theorem 2.7. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. Then $\xi = \{D^C : D \subseteq \Sigma^*, B(D) = D\}$ is a topology on Σ^* .

Proof. (i) Since $B(\emptyset) = \emptyset$, then $\Sigma^* = (\emptyset)^C \in \xi$.

(ii) Since B is a closure operator on Σ^* , $\Sigma^* \subseteq B(\Sigma^*)$. On the other hand, since $B(\Sigma^*) \in P(\Sigma^*)$, $B(\Sigma^*) \subseteq \Sigma^*$. Thus, $B(\Sigma^*) = \Sigma^*$. Therefore, we conclude that $\emptyset = (\Sigma^*)^C \in \xi$.

(iii) Let D_1^C and D_2^C belong to ξ . Then $B(D_1) = D_1$ and $B(D_2) = D_2$. Thus, we have $B(D_1 \cup D_2) = B(D_1) \cup B(D_2) = D_1 \cup D_2$. That is $D_1^C \cap D_2^C = (D_1 \cup D_2)^C \in \xi$.

(iv) Let $D_i^C \in \xi$, $\forall i \in I$. Then $B(D_i) = D_i$, $\forall i \in I$. Since B is a closure operator on Σ^* , $\bigcap_{i \in I} D_i \subseteq B(\bigcap_{i \in I} D_i)$. On the other hand, since $D_i \cup (\bigcap_{i \in I} D_i) = D_i$, so we get that $B(D_i) \cup (B(\bigcap_{i \in I} D_i)) = B(D_i)$. Then $B(\bigcap_{i \in I} D_i) \subseteq B(D_i) = D_i$. Thus $B(\bigcap_{i \in I} D_i) \subseteq \bigcap_{i \in I} D_i$. Hence, $B(\bigcap_{i \in I} D_i) = \bigcap_{i \in I} D_i$. That is, $\bigcup_{i \in I} D_i^C = (\bigcap_{i \in I} D_i)^C \in \xi$. \square

Theorem 2.8. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer, $x \in \Sigma^*$ and $A = L(\tilde{F}_r^*)$. Then

(i) $A = \iota^{-1}o\zeta$.

(ii) $x^{-1}A = (\iota * x)^{-1}o\zeta$, where $x^{-1}A = \{y \in \Sigma^* : xy \in A\}$.

Proof. (i) The proof is not complicated.

(ii) Let $y \in (\iota * x)^{-1}o\zeta$. Then $(\iota * x)(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), y, p) \wedge \zeta(p) > 0$ for some $q \in Q_{act}$, $p \in Q$. This implies that $(\iota * x)(q) > 0$ and $\tilde{\delta}^*((q, \mu^t(q)), y, p) \wedge \zeta(p) > 0$. Now $(\iota * x)(q) = \bigvee \{(\iota(r) \wedge \tilde{\delta}^*((r, \mu^t(r)), x, q) : r \in Q_{act})\} > 0$ and so

$$\iota(r) \wedge \tilde{\delta}^*((r, \mu^t(r)), x, q) > 0$$

for some $r \in Q_{act}$. Thus we have $\iota(r) \wedge \tilde{\delta}^*((r, \mu^t(r)), x, q) \wedge \tilde{\delta}^*((q, \mu^t(q)), y, p) \wedge \zeta(p) > 0$ for some $r, q \in Q_{act}$, $p \in Q$. This implies that $\iota(r) \wedge \tilde{\delta}^*((r, \mu^t(r)), xy, p) \wedge \zeta(p) > 0$ for some $r \in Q_{act}$, $p \in Q$. Thus $xy \in A$ and so $y \in x^{-1}A$.

Conversely, Let $y \in x^{-1}A$. Then $xy \in A$ and so there exist $r \in Q_{act}$, $p \in Q$ such that $\iota(r) \wedge \tilde{\delta}^*((r, \mu^t(r)), xy, p) \wedge \zeta(p) > 0$. This implies that $\tilde{\delta}^*((r, \mu^t(r)), xy, p) > 0$. Now $\tilde{\delta}^*((r, \mu^t(r)), xy, p) = \bigvee_{q \in Q_{act}} \{\tilde{\delta}^*((r, \mu^t(r)), x, q) \wedge \tilde{\delta}^*((q, \mu^t(q)), y, p)\} > 0$. Thus there exists $q \in Q_{act}$ such that $\tilde{\delta}^*((r, \mu^t(r)), x, q) \wedge \tilde{\delta}^*((q, \mu^t(q)), y, p) > 0$. So we have $\tilde{\delta}^*((r, \mu^t(r)), x, q) > 0$ and $\tilde{\delta}^*((q, \mu^t(q)), y, p) > 0$. Now $(\iota * x)(q) = \bigvee \{(\iota(s) \wedge \tilde{\delta}^*((s, \mu^t(s)), x, q) : s \in Q_{act})\} \geq \iota(r) \wedge \tilde{\delta}^*((r, \mu^t(r)), x, q) > 0$. Hence $(\iota * x)(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), y, p) \wedge \zeta(p) > 0$ for some $q \in Q_{act}$, $p \in Q$. Thus $y \in (\iota * x)^{-1}o\zeta$. \square

Theorem 2.9. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer, $x \in \Sigma^*$ and $A = L(\tilde{F}_r^*)$. Then

- (i) $x \in A$ if and only if there exists $q \in Q_{act}$ such that $[\iota \cap (\zeta * x^{-1})](q) > 0$.
- (ii) $x \in A$ if and only if there exists $p \in Q$ such that $[(\iota * x) \cap \zeta](p) > 0$.

Proof. (i) Let $x \in A$. Then there exist $q \in Q_{act}$ and $p \in Q$ such that $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$. So there exist $q \in Q_{act}$ and $p \in Q$ such that $\iota(q) > 0$ and $\tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$. Thus there exists $q \in Q_{act}$ such that $\iota(q) > 0$ and $\bigvee \{\tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) : p \in Q\} > 0$. Therefore there exists $q \in Q_{act}$ such that $\iota(q) > 0$ and $(\zeta * x^{-1})(q) > 0$. Consequently, there exists $q \in Q_{act}$ such that $[\iota \cap (\zeta * x^{-1})](q) > 0$. Similarly, we can prove the converse of this part.

(ii) Let $x \in A$. So there exist $q \in Q_{act}$ and $p \in Q$ such that $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$. Then there exist $q \in Q_{act}$ and $p \in Q$ such that $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) > 0$ and $\zeta(p) > 0$. Thus there exists $p \in Q$ such that $\bigvee \{\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) : q \in Q_{act}\} > 0$ and $\zeta(p) > 0$. Therefore there exists $p \in Q$ such that $(\iota * x)(p) > 0$ and $\zeta(p) > 0$. Consequently, there exists $p \in Q$ such that $[(\iota * x) \cap \zeta](p) > 0$. Similarly, we can show the converse of this part. \square

Definition 2.10. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer and $S_1 = \{q \in Q_{act} : (\iota * \Sigma^*)(q) > 0\}$. If $Q = S_1$, then \tilde{F}_r^* is called accessible. Consider $\tilde{\delta}^{*a} = \tilde{\delta}^*|_{\tilde{S}_1 \times \Sigma^* \times S_1}$, $\iota^a = \iota|_{S_1}$, $\zeta^a = \zeta|_{S_1}$ and $\tilde{F}_r^{*a} = (S_1, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^{*a}, F_1, F_2, \iota^a, \zeta^a)$, where $\tilde{S}_1 = \{(q, \mu^t(q)) : q \in S_1\}$. Then \tilde{F}_r^{*a} is a general fuzzy recognizer.

Definition 2.11. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. Then \tilde{F}_r^{*a} is called the accessible part of \tilde{F}_r^* .

Theorem 2.12. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. Then $L(\tilde{F}_r^*) = L(\tilde{F}_r^{*a})$.

Proof. By Theorem 2.6 (i), it is sufficient to show that $\iota^{-1}o\zeta = (\iota^a)^{-1}o\zeta^a$. Let $x \in \iota^{-1}o\zeta$. Then $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$ for some $q \in Q_{act}$, $p \in Q$. Since $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) > 0$, we have $(\iota * \Sigma^*)(p) > 0$. So $p \in S_1$. Also, since $\iota(q) > 0$ and $\tilde{\delta}^*((q, \mu^t(q)), \Lambda, q) = 1 > 0$, we have $(\iota * \Sigma^*)(q) > 0$. So $q \in S_1$. Hence $\iota^a(q) \wedge \tilde{\delta}^{*a}((q, \mu^t(q)), x, p) \wedge \zeta^a(p) > 0$ and thus $x \in (\iota^a)^{-1}o\zeta^a$. Therefore, $\iota^{-1}o\zeta \subseteq (\iota^a)^{-1}o\zeta^a$.

Now, let $x \in (\iota^a)^{-1}o\zeta^a$. Then $\iota^a(q) \wedge \tilde{\delta}^{*a}((q, \mu^t(q)), x, p) \wedge \zeta^a(p) > 0$ for some $q, p \in S_1$. Therefore $\iota^a(q) > 0$, $\tilde{\delta}^{*a}((q, \mu^t(q)), x, p) > 0$ and $\zeta^a(p) > 0$. Thus $\iota(q) = \iota^a(q)$, $\zeta(p) = \zeta^a(p)$ and $\tilde{\delta}^*((q, \mu^t(q)), x, p) = \tilde{\delta}^{*a}((q, \mu^t(q)), x, p)$. Consequently, $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$. Hence $x \in \iota^{-1}o\zeta$. So $(\iota^a)^{-1}o\zeta^a \subseteq \iota^{-1}o\zeta$. \square

Theorem 2.13. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer and $S_1 = \{q \in Q_{act} : (\iota * \Sigma^*)(q) > 0\}$. We define on S_1 the following hyperoperation :

$$p \circ p = \{r \in S_1 : (\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r)\},$$

and

$$p \circ q = (p \circ p) \cup (q \circ q), \text{ where } p \neq q.$$

Then $\langle S_1, \circ \rangle$ is a commutative hypergroup.

Proof. We first show that the hyperoperation " \circ " is associative. We have

$$\begin{aligned} (p \circ q) \circ s &= [\{r_1 \in S_1 : (\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r_1)\} \cup \{r_2 \in S_1 : (\iota * \Sigma^*)(q) \geq (\iota * \Sigma^*)(r_2)\}] \circ s \\ &= \{r'_1 \in S_1 : (\iota * \Sigma^*)(r_1) \geq (\iota * \Sigma^*)(r'_1), (\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r_1)\} \\ &\cup \{r'_2 \in S_1 : (\iota * \Sigma^*)(r_2) \geq (\iota * \Sigma^*)(r'_2), (\iota * \Sigma^*)(q) \geq (\iota * \Sigma^*)(r_2)\} \\ &\cup \{r_3 \in S_1 : (\iota * \Sigma^*)(s) \geq (\iota * \Sigma^*)(r_3)\} \\ &\subseteq \{r'_1 \in S_1 : (\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r'_1)\} \cup \{r'_2 \in S_1 : (\iota * \Sigma^*)(q) \geq (\iota * \Sigma^*)(r'_2)\} \\ &\cup \{r_3 \in S_1 : (\iota * \Sigma^*)(s) \geq (\iota * \Sigma^*)(r_3)\}. \end{aligned}$$

Let

$$T = \{r_1 \in S_1 : (\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r_1)\} \cup \{r_2 \in S_1 : (\iota * \Sigma^*)(q) \geq (\iota * \Sigma^*)(r_2)\} \\ \cup \{r_3 \in S_1 : (\iota * \Sigma^*)(s) \geq (\iota * \Sigma^*)(r_3)\}.$$

Thus $(p \circ q) \circ s \subseteq T$. Now, let $r \in \{r_1 \in S_1 : (\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r_1)\}$. Then $(\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r)$. Hence $r \in p \circ p \subseteq (p \circ q) \circ s$. So $(p \circ q) \circ s \supseteq T$. Therefore

$$(p \circ q) \circ s = T.$$

Similarly,

$$p \circ (q \circ s) = T.$$

Therefore the hyperoperation " \circ " is associative. We claim that

$$S_1 \circ q = q \circ S_1 = S_1, \quad \forall q \in S_1.$$

It is clear that $S_1 \circ q \subseteq S_1$. For the reverse inclusion, let $p \in S_1$. Since $(\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(p)$, hence

$$p \in \{r_1 \in S_1 : (\iota * \Sigma^*)(p) \geq (\iota * \Sigma^*)(r_1)\} \cup \{r_2 \in S_1 : (\iota * \Sigma^*)(q) \geq (\iota * \Sigma^*)(r_2)\} = p \circ q.$$

Thus $p \in S_1 \circ q$. So $S_1 \subseteq S_1 \circ q$. \square

Definition 2.14. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. \tilde{F}_r^* is called complete if for all $q \in Q_{act}$, $x \in \Sigma^*$, there exists $p \in Q$ such that $\tilde{\delta}^*((q, \mu^t(q)), x, p) > 0$.

Theorem 2.15. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a complete general fuzzy recognizer, then so is \tilde{F}_r^{*a} .

Proof. Let $(q, x) \in S_1 \times \Sigma^*$. Then $(q, x) \in Q_{act} \times \Sigma^*$. Since \tilde{F}_r^* is complete, there exists $p \in Q$ such that $\tilde{\delta}^*((q, \mu^t(q)), x, p) > 0$. Now $q \in S_1$, then $(\iota * \Sigma^*)(q) > 0$. So there exist $p_0 \in Q_{act}$ and $x_0 \in \Sigma^*$ such that $\iota(p_0) \wedge \tilde{\delta}^*((p_0, \mu^t(p_0)), x_0, q) > 0$. This implies that $\iota(p_0) > 0$ and $\tilde{\delta}^*((p_0, \mu^t(p_0)), x_0, q) > 0$. Hence $\tilde{\delta}^*((p_0, \mu^t(p_0)), x_0, q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) > 0$. Now $\tilde{\delta}^*((p_0, \mu^t(p_0)), x_0 x, p) = \bigvee_{r \in Q_{act}} \{\tilde{\delta}^*((p_0, \mu^t(p_0)), x_0, r) \wedge \tilde{\delta}^*((r, \mu^t(r)), x, p)\} > 0$. Hence $\iota(p_0) \wedge \tilde{\delta}^*((p_0, \mu^t(p_0)), x_0 x, p) > 0$. Therefore, $(\iota * \Sigma^*)(p) > 0$ and so $p \in S_1$. Since $\tilde{\delta}^{*a}((q, \mu^t(q)), x, p) = \tilde{\delta}^*((q, \mu^t(q)), x, p)$, \tilde{F}_r^{*a} is complete. \square

Definition 2.16. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer and $S_2 = \{q \in Q_{act} : (\zeta * (\Sigma^*)^{-1})(q) > 0\}$. If $Q = S_2$, then \tilde{F}_r^* is called coaccessible.

Consider $\tilde{\delta}^{*b} = \tilde{\delta}^*|_{\tilde{S}_2 \times \Sigma^* \times \tilde{S}_2}$, $\iota^b = \iota|_{S_2}$, $\zeta^b = \zeta|_{S_2}$ and $\tilde{F}_r^{*b} = (S_2, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^{*b}, F_1, F_2, \iota^b, \zeta^b)$, where $\tilde{S}_2 = \{(q, \mu^t(q)) : q \in S_2\}$. Then \tilde{F}_r^{*b} is a general fuzzy recognizer.

Definition 2.17. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. Then \tilde{F}_r^{*b} is called the coaccessible part of \tilde{F}_r^* .

Theorem 2.18. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. Then $L(\tilde{F}_r^*) = L(\tilde{F}_r^{*b})$.

Proof. By Theorem 2.8 (i), it is sufficient to show that $\iota^{-1}o\zeta = (\iota^b)^{-1}o\zeta^b$. Let $x \in \iota^{-1}o\zeta$. Then $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$ for some $q \in Q_{act}$, $p \in Q$. Since $\tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$, we have $(\zeta * (\Sigma^*)^{-1})(q) > 0$. So $q \in S_2$. Also, since $\zeta(p) > 0$ and $\tilde{\delta}^*((p, \mu^t(p)), \Lambda, p) = 1 > 0$, $(\zeta * (\Sigma^*)^{-1})(p) > 0$. So $p \in S_2$. Hence $\iota^b(q) \wedge \tilde{\delta}^{*b}((q, \mu^t(q)), x, p) \wedge \zeta^b(p) > 0$ and thus $x \in (\iota^b)^{-1}o\zeta^b$. Therefore

$$\iota^{-1}o\zeta \subseteq (\iota^b)^{-1}o\zeta^b.$$

Now, let $x \in (\iota^b)^{-1}o\zeta^b$. Then $\iota^b(q) \wedge \tilde{\delta}^{*b}((q, \mu^t(q)), x, p) \wedge \zeta^b(p) > 0$ for some $q, p \in S_2$. Therefore $\iota^b(q) > 0$, $\tilde{\delta}^{*b}((q, \mu^t(q)), x, p) > 0$ and $\zeta^b(p) > 0$. Thus $\iota(q) = \iota^b(q)$, $\zeta(p) = \zeta^b(p)$ and $\tilde{\delta}^*((q, \mu^t(q)), x, p) = \tilde{\delta}^{*b}((q, \mu^t(q)), x, p)$. Consequently, $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$. Hence $x \in \iota^{-1}o\zeta$. So $(\iota^b)^{-1}o\zeta^b \subseteq \iota^{-1}o\zeta$. \square

Theorem 2.19. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer and $S_2 = \{q \in Q_{act} : (\zeta * (\Sigma^*)^{-1})(q) > 0\}$. We define on S_2 the following hyperoperation :

$$p \circ p = \{r \in S_2 : (\zeta * (\Sigma^*)^{-1})(p) \geq (\zeta * (\Sigma^*)^{-1})(r)\},$$

and

$$p \circ q = (p \circ p) \cup (q \circ q), \text{ where } p \neq q.$$

Then $\langle S_2, \circ \rangle$ is a commutative hypergroup.

Proof. The proof is similar to Theorem 2.13, by using suitable modification. \square

Definition 2.20. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. Define $\tilde{\delta}^{*\rho}((p, \mu^s(p)), x, q) = \tilde{\delta}^*((q, \mu^t(q)), \rho(x), p)$, $\forall p, q \in Q_{act}, \forall x \in \Sigma^*$. Then the general fuzzy recognizer $\tilde{F}_r^{*\rho} = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^{*\rho}, F_1, F_2, \zeta, \iota)$ is called the reversal of \tilde{F}_r^* .

Theorem 2.21. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer. If $Q = Q_{act}$, then $L(\tilde{F}_r^{*\rho}) = [L(\tilde{F}_r^*)]^\rho$.

Proof. By Theorem 2.8 (i), it is sufficient to show that $\zeta^{-1}o\iota = [\iota^{-1}o\zeta]^\rho$. Let $\rho(x) \in [\iota^{-1}o\zeta]^\rho$. Then $x \in \iota^{-1}o\zeta$. This implies that $\iota(q) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) \wedge \zeta(p) > 0$ for some $q \in Q_{act}, p \in Q$. Since $Q = Q_{act}$, so $\zeta(p) \wedge \tilde{\delta}^{*\rho}((p, \mu^s(p)), \rho(x), q) \wedge \iota(q) > 0$ for some $p \in Q_{act}, q \in Q$. Therefore $\rho(x) \in \zeta^{-1}o\iota$. Consequently, $[\iota^{-1}o\zeta]^\rho \subseteq \zeta^{-1}o\iota$. Similarly, we can prove that $\zeta^{-1}o\iota \subseteq [\iota^{-1}o\zeta]^\rho$. \square

Theorem 2.22. Let $\tilde{F}_r^* = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^*, F_1, F_2, \iota, \zeta)$ be a general fuzzy recognizer and $Q = Q_{act}$. Then \tilde{F}_r^* is coaccessible if and only if $\tilde{F}_r^{*\rho}$ is accessible.

Proof. Let \tilde{F}_r^* be coaccessible. By Definition 2.16, we have $Q = \{q \in Q_{act} : (\zeta * (\Sigma^*)^{-1})(q) > 0\}$. Then for all $q \in Q$, there exist $x \in \Sigma^*$ and $p \in Q$ such that $\zeta(p) \wedge \tilde{\delta}^*((q, \mu^t(q)), x, p) > 0$. Since $Q = Q_{act}$, for all $q \in Q$, there exist x^ρ namely $\rho(x) \in \Sigma^*$ and $p \in Q_{act}$ such that $\zeta(p) \wedge \tilde{\delta}^{*\rho}((p, \mu^s(p)), \rho(x), q) > 0$. So $Q = \{q \in Q_{act} : (\zeta * \Sigma^*)(q) > 0\}$. Therefore $\tilde{F}_r^{*\rho} = (Q, \Sigma, \tilde{R}, Z, \omega, \tilde{\delta}^{*\rho}, F_1, F_2, \zeta, \iota)$ is accessible. Similarly, we can verify the converse of this theorem. \square

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